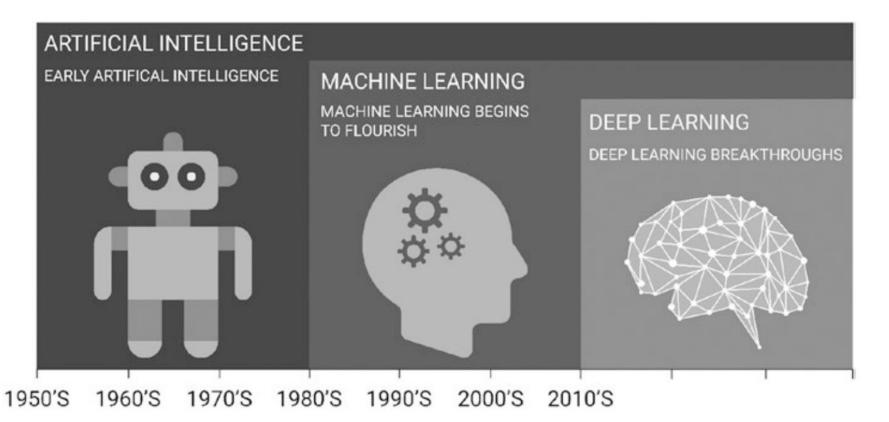
介紹AI深度學習

陽明大學 醫務管理研究所 陳 翎 助理教授

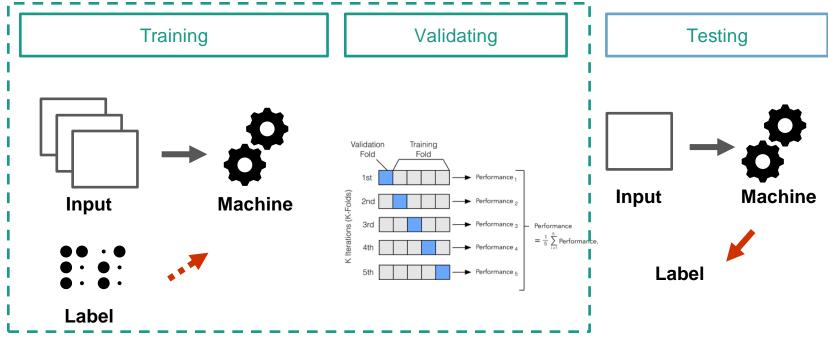
Machine Learning Recap

Concept Relationship



Panesar, A. (2019). Machine Learning and Al for Healthcare. In Machine Learning and Al for Healthcare. Ch 1.

Machine Learning Pipeline



Cross-validation image: http://ethen8181.github.io/machine-learning/model_selection/model_selection.html

What exactly does a machine learn?

 $argmin_{w}E(||Goal - F(x, w)||)$

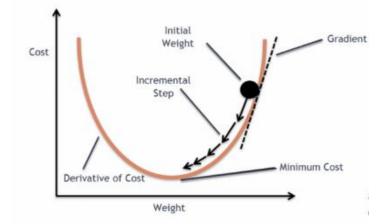


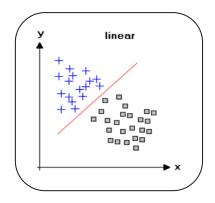
Image: https://blog.clairvoyantsoft.com/the-ascent-of-gradient-descent-23356390836f

What exactly does a machine learn?

$$argmin_{w}E(||Goal - F(x, w)||)$$

 \rightarrow Example

$$MSE = \frac{1}{N} \sum_{i=1}^{n} (y_i - f(x_i))^2$$



Vector, Matrix, Tensor





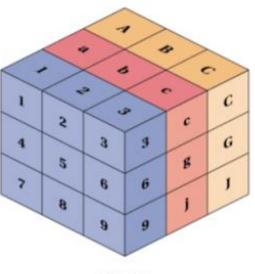


ſ	4	19	8	1
l	16	3	5	J



Row Vector (shape 1x3) Column Vector (shape 3x1)

MATRIX



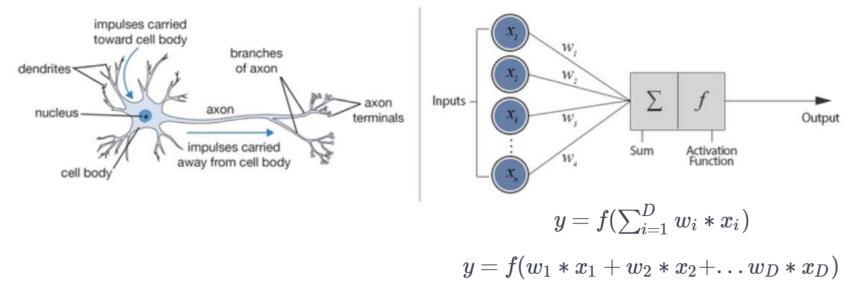


https://dev.to/mmithrakumar/scalars-vectors-matrices-and-tensors-with-tensorflow-2-0-1f66

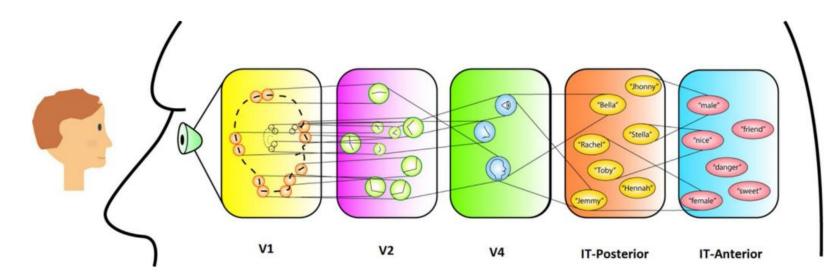
Deep Learning Basics

Neural Networks

Biological Neuron versus Artificial Neural Network



Deep learning: layers of abstraction

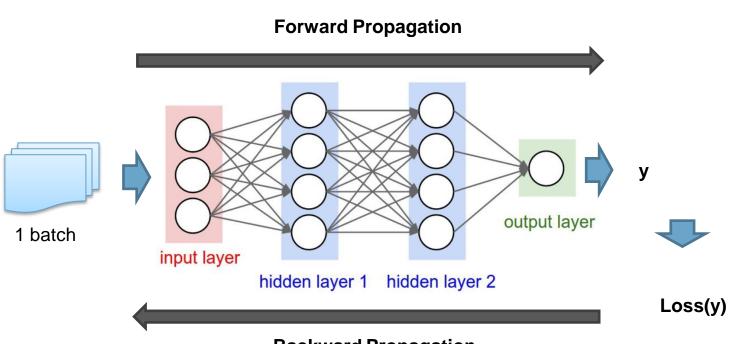


Saba, L., Biswas, M., Kuppili, V., Cuadrado Godia, E., Suri, H. S., Edla, D. R., Omerzu, T., Laird, J. R., Khanna, N. N., Mavrogeni, S., Protogerou, A., Sfikakis, P. P., Viswanathan, V., Kitas, G. D., Nicolaides, A., Gupta, A., & Suri, J. S. (2019). The present and future of deep learning in radiology. *European Journal of Radiology*, *114*(February), 14–24.

Basic Concepts for Training

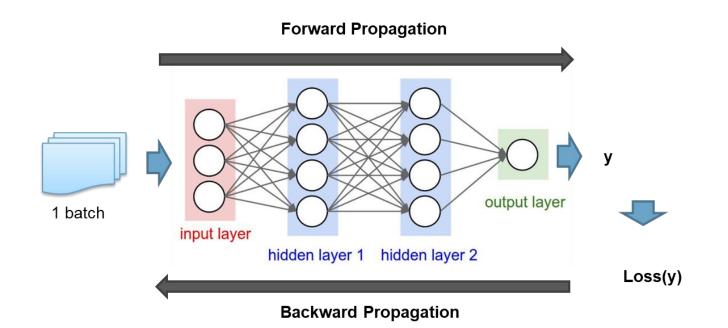
Epoch Batch Iteration • One The entire The iteration dataset is number of over the divided into batch runs entire a number over one dataset of batches epoch

One iteration...

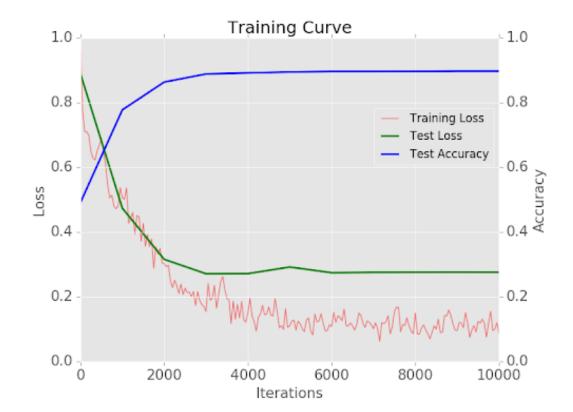


Backward Propagation

Batch size matters, why?

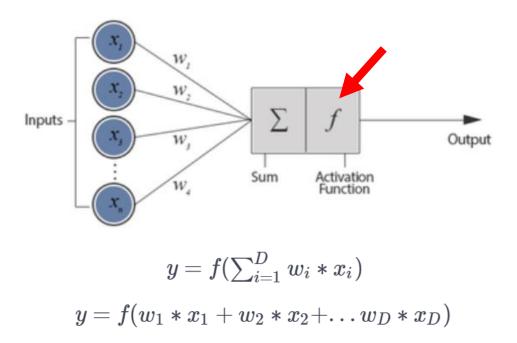


Training curve



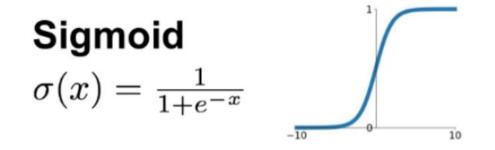
Common Activation Functions

Activation Function



https://www.analyticsvidhya.com/blog/2017/05/25-must-know-terms-concepts-for-beginners-in-deep-learning/

Sigmoid



 ${\tt tf.keras.activations.sigmoid(x)}$

https://medium.com/hyunjulie/activation-functions-a-short-summary-8450c1b1d426

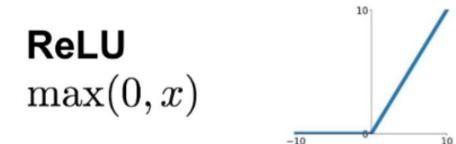
Tanh



tf.keras.activations.tanh(x)

https://medium.com/hyunjulie/activation-functions-a-short-summary-8450c1b1d426

Rectified Linear Unit (ReLU)



Advantages:

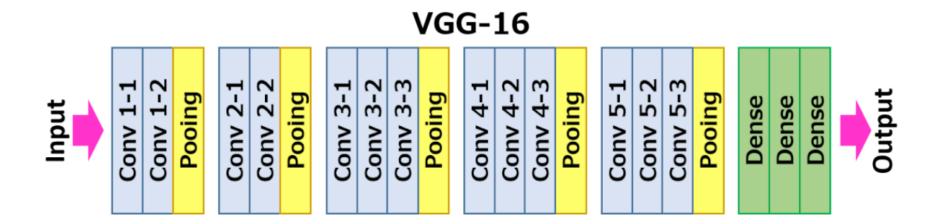
- Handles vanishing gradient problem
- Non-saturating: not squashing real numbers to a range
- Faster convergence

tf.keras.activations.relu(x, alpha=0.0, max_value=None, threshold=0)

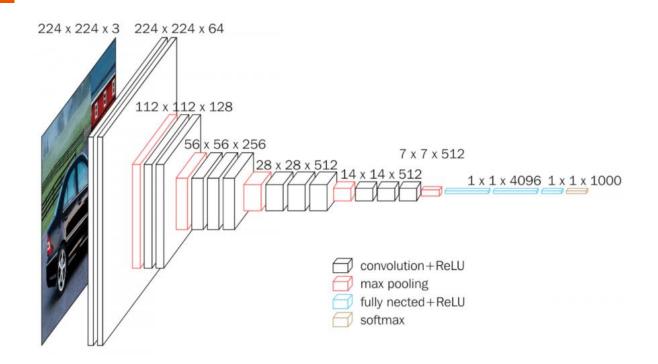
https://medium.com/hyunjulie/activation-functions-a-short-summary-8450c1b1d426

Commonly used layers

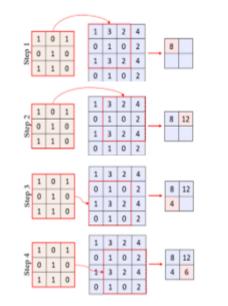
What does this network mean?

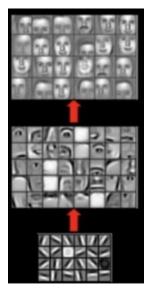


And this one?



Convolution Layer





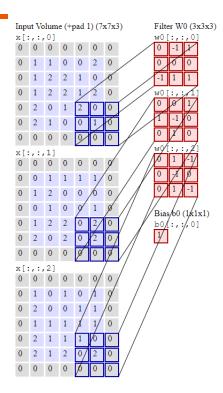
Output size = (W-F+2P)/S+1

W: input volume sizeF: filter/channel sizeP: the amount of zero padding usedS: the stride with which they are applied

This example: (4-3+2*0)/1+1 = 2

https://www.topbots.com/advanced-topics-deep-convolutional-neural-networks/

Convolutional Layer



	x3x3)		Output Volume (3x3x2)								
	0]	_	o[:,:,0] 6 0 0						
1	0	-1		9	4	0					
0	0	1		-		-					
	× :,:	-	1		~ ,:,						
	-1		1		1	_					
1	-1	-1		-6	1	-4					
0	-1	-1		2	-2	-7					
w1	w1[:,:,2]										
-1	1	1									
0	0	1									
-1	-1	0									
Bias b1 (1x1x1) b1[:,:,0]											

toggle movement

Output size = (W-F+2P)/S+1

This example: $(5-3+2^{1})/2+1=3$

Convolutional Layer

Conv2D layer

Conv2D class

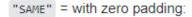
tf.keras.layers.Conv2D(
filters,
kernel_size,
<pre>strides=(1, 1),</pre>
<pre>padding="valid",</pre>
data_format=None,
<pre>dilation_rate=(1, 1),</pre>
groups=1,
activation=None,
use_bias=True,

Padding

"VALID"	= wit	hout	pad	ding:
---------	-------	------	-----	-------

inputs:	1 	2	3	4	5	6	7	8	9	10 11	(12 13) dropped

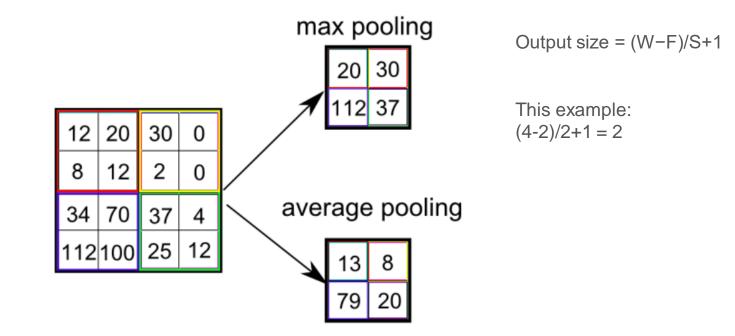
With "VALID" padding, there's no "made-up" padding inputs. The layer only uses valid input data.





"SAME" tries to pad evenly left and right, but if the amount of columns to be added is odd, it will add the extra column to the right, as is the case in this example

Pooling Layer



https://medium.com/analytics-vidhya/convolutional-neural-network-cnn-1bd606078aa5

Pooling Layer

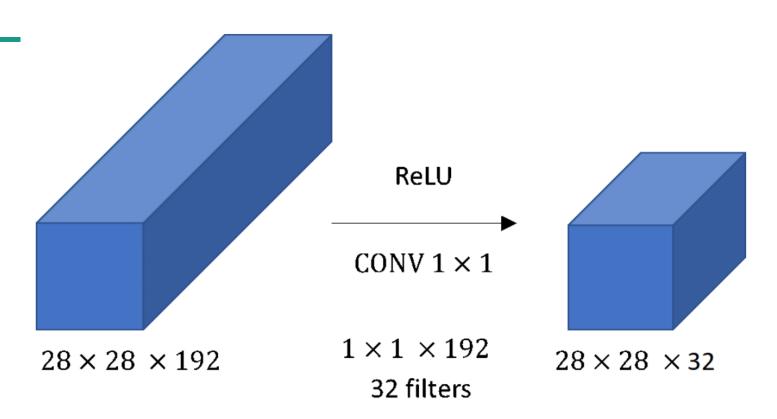
MaxPooling2D layer

MaxPooling2D class

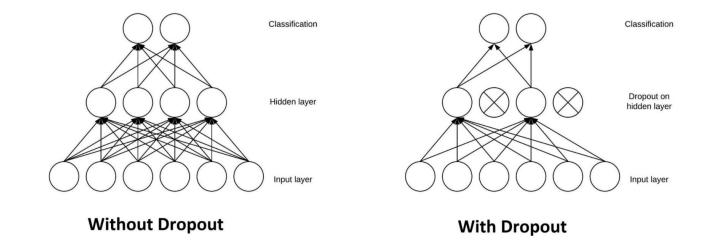
```
tf.keras.layers.MaxPooling2D(
    pool_size=(2, 2), strides=None, padding="valid", data_format=None, **kwargs
)
```

https://medium.com/analytics-vidhya/convolutional-neural-network-cnn-1bd606078aa5

Using 1x1 Convolution



Dropout Layer



Dropout Layer

Dropout layer

Dropout class

tf.keras.layers.Dropout(rate, noise_shape=None, seed=None, **kwargs)

tf.keras.layers.Dropout(.2, input_shape=(2,))

https://keras.io/api/layers/regularization_layers/dropout/

Output Layer

sigmoid function

tf.keras.activations.sigmoid(x)

Sigmoid activation function, sigmoid(x) = 1 / (1 + exp(-x)).

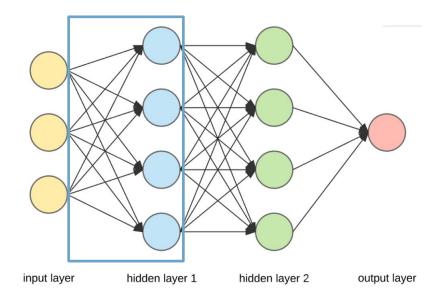
softmax function

tf.keras.activations.softmax(x, axis=-1)

The softmax of each vector x is computed as $exp(x) / tf.reduce_sum(exp(x))$.

https://keras.io/api/layers

Dense/Fully Connected Layer



Dense/Fully Connected Layer

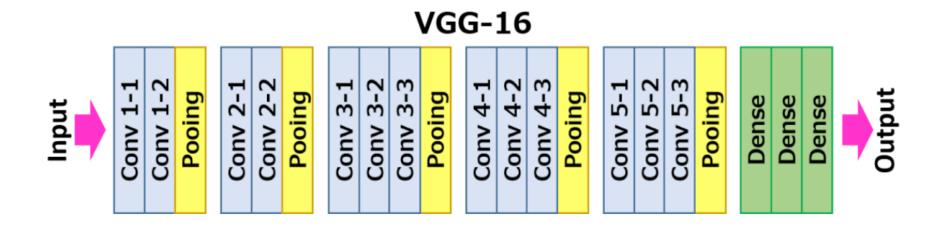
Dense class

tf.keras.layers.Dense(
 units,
 activation=None,
 use_bias=True,
 kernel_initializer="glorot_uniform",
 bias_initializer="zeros",
 kernel_regularizer=None,
 bias_regularizer=None,
 activity_regularizer=None,
 kernel_constraint=None,
 bias_constraint=None,
 **kwargs

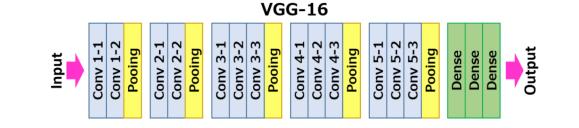
)

https://keras.io/api/layers/core_layers/dense/

Now can you read this network?



A simple line of code...

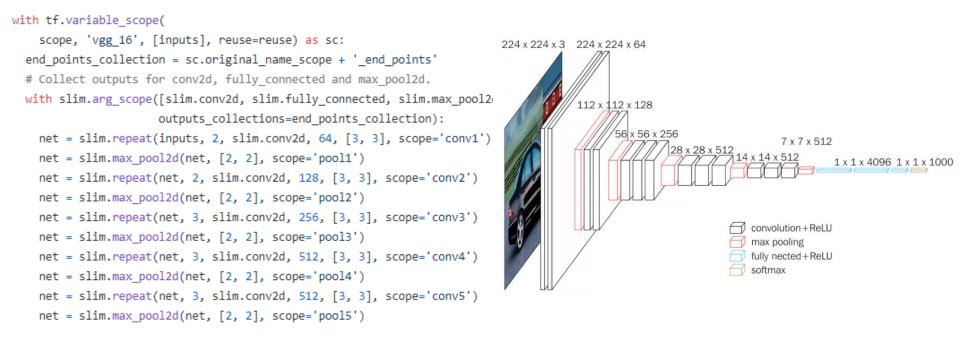




```
tf.keras.applications.VGG16(
    include_top=True, weights='imagenet', input_tensor=None, input_shape=None,
    pooling=None, classes=1000, classifier_activation='softmax'
)
```

https://www.tensorflow.org/api_docs/python/tf/keras/applications/VGG16

Behind the code...



https://github.com/tensorflow/models/blob/master/research/slim/nets/vgg.py#L147; https://neurohive.io/en/popular-networks/vgg16/

Common Loss Functions

Learning is an Optimization Problem

Typically, a neural network model is trained using the **stochastic gradient descent** optimization algorithm and weights are updated using the **backpropagation**.

 $argmin_{w}E(||Goal - F(x, w)||)$

"The function we want to minimize or maximize is called the objective function or criterion. When we are minimizing it, we may also call it the cost function, loss function, or error function."

Goodfellow, I., Bengio, Y., Courville, A., & Bengio, Y. (2016). Deep learning (Vol. 1, Issue 2). MIT press Cambridge.

Loss Function

Regression

MSE =
$$\frac{1}{N} \sum_{i=1}^{N} (y_i - \hat{y}_i)^2$$

$$MAE = \frac{1}{N} \sum_{i=1}^{N} |y_i - \hat{y}_i|$$

Loss Function

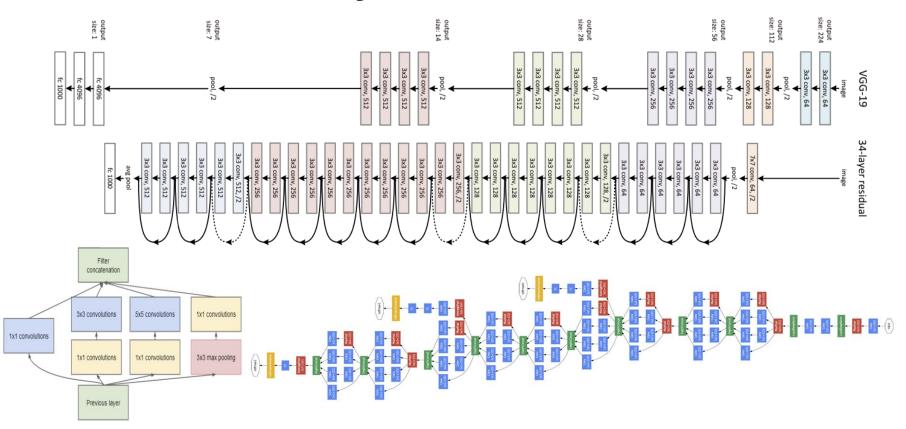
Classification – cross-entropy

$$I(x) = -log_2(p(x))$$

$$H = \sum_{c=1}^{C} \sum_{i=1}^{n} -y_{c,i} \log_2(p_{c,i})$$

Standing on the shoulders of giants

Commonly used backbones

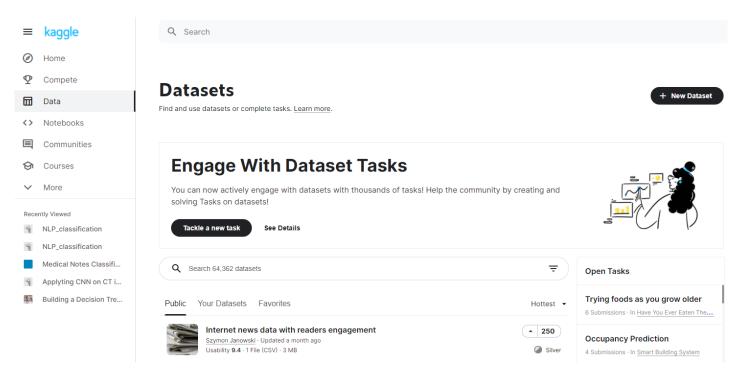


YOSHUA BENGIO, GEOFFREY E. HINTON AND YANN LECUN

For conceptual and engineering breakthroughs that have made deep neural networks a critical component of computing

What's Next?

Kaggle



https://www.kaggle.com/

Example CNN

```
model2 = Sequential()
model2.add(Conv2D(50, (5, 5), activation='relu', input_shape=input_shape))
model2.add(MaxPooling2D(pool_size=(3, 3))) # 3x3 Maxpooling
model2.add(Conv2D(30, (4, 4), activation='relu', input_shape=input_shape))
model2.add(MaxPooling2D(pool_size=(2, 2))) # 2x2 Maxpooling
model2.add(Flatten())
model2.add(Dense(2, activation='softmax'))
```

Thank You 🕲

請多多指教!

